



US 20190127064A1

(19) **United States**(12) **Patent Application Publication** (10) **Pub. No.: US 2019/0127064 A1**
(43) **Pub. Date:** **May 2, 2019**(54) **DRONE-BASED PAINTING SYSTEM**(71) Applicants: **DISNEY ENTERPRISES, INC.**,
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SAI VEMPATI, ZURICH (CH)(21) Appl. No.: **15/798,601**(22) Filed: **Oct. 31, 2017****Publication Classification**(51) **Int. Cl.**
B64C 39/02 (2006.01)
B05B 13/02 (2006.01)
B05B 13/04 (2006.01)
B05B 9/04 (2006.01)
G05D 1/08 (2006.01)(52) **U.S. Cl.**CPC **B64C 39/024** (2013.01); **B05B 13/0278**
(2013.01); **B05B 13/04** (2013.01); **B64C**
2201/141 (2013.01); **G05D 1/085** (2013.01);
B64C 2201/12 (2013.01); **B05B 9/0426**
(2013.01)

(57)

ABSTRACT

A painting system that makes use of drones such as modified quadrotors. The drone includes a support arm that carries a paint nozzle configured for pan and tilt motion. A power supply line is connected from an external power supply to the drone to allow extended flight time. A paint supply line is also connected from an external paint supply to the drone to allow extended painting time and/or surface coverage with each flight. The drone has an onboard controller so painting is autonomous with no human input being required. The drone stores a 3D model of the target structure annotated with the drone trajectory plus commands to control the pan-tilt paint nozzle to perform the painting. At runtime, the controller uses a sensor to view the target structure and localizes itself. The drone then traverses the stored trajectory and implements the painting commands to paint the 3D structure's surfaces.

